

AMENDMENTS TO THE CLAIMS

This listing of claims replaces all prior versions, and listings, of claims in the application:

1. – 8. (Canceled):

9. (New): A component placement device comprising:

a movable frame;

at least two component pick and place units that are connected to the movable frame;

and

at least two component feeding devices,

wherein the component placement device is configured to simultaneously pick-up components, by means of the component pick and place units, supplied by the component feeding devices, and

wherein at least one component pick and place unit is configured to be moved relative to the frame such that the respective positions of the component pick and place units are adjusted.

10. (New): The component placement device according to claim 9, wherein each component pick and place unit is configured to be moved relative to the frame.

11. (New): The component placement device according to claim 9,

wherein a first of the component pick and place units is configured to be moved, in a first direction, relative to a second of the component pick and place units while the components that are to be supplied by means of the component feeding devices are moved relative to one another in a second direction, and

wherein the second direction is transverse to the first direction.

12. (New): A method for picking-up components by means of a component placement device that is provided with a movable frame; at least two component pick and place units that are connected to the movable frame; and at least two component feeding devices, the method comprising the steps of:

setting components and the pick and place units relative to one another; and  
picking-up the components simultaneously using each of the component pick and place units.

13. (New): The method according to claim 12, further comprising the step of:  
adjusting the positions of the component pick and place units by moving at least one component pick and place unit relative to the frame.

14. (New): The method according to claim 12, further comprising the steps of:  
detecting, using a camera, the positions of the components to be picked-up from the component feeding devices; and  
adjusting the positions of the component pick and place units on the basis of the positions of the components to be picked-up.

15. (New): The method according to claim 12, further comprising the steps of:  
determining actual positions of the components picked-up by the component pick and place units relative to the component pick and place units;  
determining deviations, if any, between desired positions of the components and the actual positions of the components; and  
moving, based on the deviations, the component pick and place units relative to one another prior to the step of picking-up the components.

16. (New): The method according to claim 12, further comprising the steps of:  
moving the pick and place units relative to one another in a first direction; and  
simultaneously  
moving, by means of the component feeding devices, the components to be picked-up relative to one another in a second direction that extends transverse to the first direction.